HS 2013

# Distributed Systems Part II 

## Solution to Exercise Sheet 9

## 1 Clock Synchronization: Spanning Tree

We want to show that the stretch of the spanning tree is at least $m$ in every grid of $n=m \times m$ nodes. In other words, there exist two neighboring nodes that are distance $m$ apart in the spanning tree of the grid. We choose an arbitrary Node A as the root node of the spanning tree, see Figure 1. Starting from the root node, we walk between the cells of the grid until we get out of the grid. Since there exists no cycles in a tree, every cell is bounded by at most 3 edges that are part of the spanning tree. Thus, starting from the root node, we can always find a sequence of cells we have to visit to find a way out of the grid. We denote the nodes adjacent to the cell where we leave the grid as Node B and Node C. Consequently, both Node B and Node C have to be neighbors in the grid and both nodes are part of the spanning tree. When travelling from Node B to C (and vice versa) it is necessary to take a detour over the root node since the path between the cells from the root to the outside of the grid never crossed an edge of the spanning tree. Thus, even in the best case where the network diameter is $\frac{m}{2}$, the neighboring nodes B and C have at least a distance of $m$ in the spanning tree. This leads to a stretch of the spanning tree of at least $m$.


Figure 1: Node A is the root node of the spanning tree (only partially shown). The dashed line is a path between the grid cells from the root node to the outside of the grid.

## 2 Network Updates

a) $v_{3}$ can not change before $v_{2}$, but $v_{2}$ needs to wait for $v_{1}$, requiring three steps in total.


Figure 2: Graph with three rules.
b) Let $E^{\prime}$ be the set of rules that no longer need to be updated and $V^{\prime}$ the set of nodes with the property that there exists a path to the destination using only rules from $E^{\prime}$, with $d \in V^{\prime}$. Any new rule with the property that it points to a node from $V^{\prime}$ can not induce a cycle, since all paths from all nodes from $V^{\prime}$ end at $d$ and $d$ has no outgoing edge. If there are still rules to be updated, then such a rule will always exist, since the set of new rules induces a directed tree with $d$ as its root and all edges in this tree are oriented towards $d$, meaning at least one new rule will point to a node from $V^{\prime}$.

Note: As seen in c), all rules that can be updated might have this property.
c) For a graph with $n$ nodes we use the same concept as in the first item, but with $n$ instead of three vertices $v_{i}$. Again, $v_{i}$ can not change before $v_{i-1}$ for $2 \leq i \leq n$, requiring $n$ steps in total.


Figure 3: Graph with $n$ rules.
d) Obviously, $v_{3}$ can always change in the first step, without any consequences for the other nodes - see $\mathbf{b}$ ). But what about $v_{2}$ and $v_{1}$ ? If $v_{1}$ changes in the first step, then updating $v_{2}$ would induce a cycle, and vice versa. Therefore two possible ways to migrate the network would be:

- Migrate $v_{3}$ and $v_{1}$ in the first step. Migrate $v_{2}$ in the second step.
- Migrate $v_{3}$ and $v_{2}$ in the first step. Migrate $v_{1}$ in the second step.

