



# Principles of Distributed Computing

## Exercise 1: Sample Solution

### 1 Vertex Coloring

- a) In the lecture, we have seen that Algorithm 1.9 (“Reduce”) of the lecture notes needs  $M$  rounds to complete when started with a valid initial coloring of colors between 1 and  $M$ . If the initial colors are unique node IDs, this is  $O(n)$  if all IDs are in  $O(n)$ . However, if we for example assume that IDs are arbitrary  $O(\log n)$ -bit numbers, the number of possible IDs can be any polynomial in  $n$  and the time complexity of Algorithm 1.9 is not linear any more.

Algorithm 1.9 works because it guarantees that no two neighbors in the graph  $G$  assign a new color simultaneously. If we are able to design an algorithm for which this condition still holds but which assigns a new color in every communication round, we are done. Algorithm 1 which is synchronously executed by all nodes fulfills these requirements.

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**Algorithm 1** “ $\Delta + 1$ ”-Coloring in  $O(n)$  Rounds

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- 1: **send** node ID to all neighbors.
  - 2: **while** no color assigned **do**
  - 3:   **if** ID is lowest among all un-colored neighbors **then**
  - 4:     choose smallest possible color
  - 5:     **send** chosen color to all neighbors
  - 6:   **end if**
  - 7: **end while**
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In each (but the first) round at least the un-colored node with the lowest ID in the graph assigns a color. Therefore, the algorithm terminates after at most  $n + 1$  rounds.

- b) Each node sends exactly two messages to each neighbor, one in the first round and one after assigning a color. Therefore, the total number of messages is  $4 \cdot m$  where  $m$  denotes the number of edges in the graph.
- c) Yes, the algorithm still works, it could be reformulated in the following way (we assume that each node knows its degree):

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**Algorithm 2** Asynchronous “ $\Delta + 1$ ”-Coloring

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- 1: **send** node ID to all neighbors.
  - 2: wait until all neighbor IDs have been received and all neighbors with a lower ID have chosen a color
  - 3: choose smallest possible color
  - 4: **send** chosen color to all neighbors
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**Algorithm 3** Counting Nodes I

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1: wait until receiving a request to count the nodes of sub-tree (originator of this request is the
   parent node)
2: if I am a leaf then
3:   send 1 back to the parent node
4: else
5:   send request for counting to all children
6:   wait until all children have sent the sizes of their sub-trees
7:   send 1 + sum of the sizes of the children sub-trees to the parent node
8: end if
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## 2 Counting the Nodes of a Tree

- a) For convenience, we define  $v$  as the root of tree  $T$ .  $v$  starts the algorithm by asking all of its children about the sizes of their sub-trees. Each node then performs the above Algorithm 3.

The “request” messages have to travel all the way down to the leafs of the tree and after arriving there, the “result”-messages travel all the way up to the root  $v$  of the tree. The time complexity of this algorithm is therefore  $2 \cdot h$  where  $h$  is the height of the tree. This holds for the synchronous and for the asynchronous variant of the algorithm.

- b) Essentially, we can simultaneously execute the second phase of the above algorithm for all possible root nodes. The algorithm can be formulated as follows:

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**Algorithm 4** Counting Nodes II

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1: if I am a leaf then
2:   send 1 back to the parent node (the only neighbor)
3: else
4:   wait until all but one neighbors have sent the sizes of their sub-trees.
5:   send 1 + sum of the sizes of the sub-trees to the neighbor  $u$  which has not yet sent the size
   of its sub-tree.
6:   wait until the last neighbor  $u$  has sent the size of its sub-tree
7:   for all neighbors  $w$  except  $u$  do
8:     send 1 + sum of the sizes of the sub-trees of the other neighbors to  $w$ 
9:   end for
10: end if
11: Calculate the number of nodes as 1 + the sum of all received sub-tree sizes
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Each node sends exactly one message to each neighbor, the message complexity is therefore  $2(n-1)$  ( $n-1$  is the number of edges of a tree). The time complexity is  $O(\text{diameter}(G))$ .

- c) First, we prove that no neighbor of  $v$  can have a sub-tree whose size is greater than  $n/2$  (note that having size exactly  $n/2$  is not possible because we defined  $n$  to be odd). For the sake of contradiction, assume that  $v$  has a neighbor  $w$  whose sub-tree has a size  $s_w > n/2$ . When dividing  $T$  at  $v$ , we get a  $s_w : (n - s_w - 1)$ -partition. When dividing  $T$  at  $w$ , we can get a  $(s_w - 1) : (n - s_w)$ -partition which is better.

Second, we prove that there is a unique node  $v$  for which all neighboring sub-trees are smaller than  $n/2$ . Such a node  $v$  exists because all other nodes have a neighbor which achieves a better partition of the tree. There must be at least one optimal node. Further  $v$  is unique because for all neighbors  $w$  of  $v$ , the sub-tree rooted at  $v$  has a size which is greater than  $n/2$ .

The worst that can happen is that  $v$  has three equal neighbors. For the partition, we then get a 1 : 2 ratio.