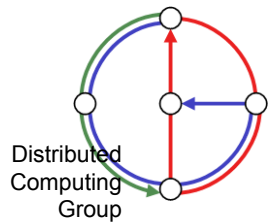


Chapter 8

DOMINATING SETS



Mobile Computing
Summer 2004

Overview

- Motivation
- Dominating Set
- Connected Dominating Set

- The “Greedy” Algorithm
- The “Tree Growing” Algorithm
- The “Marking” Algorithm
- The “k-Local” Algorithm
- The “Dominator!” Algorithm
- The “Largest ID” Algorithm



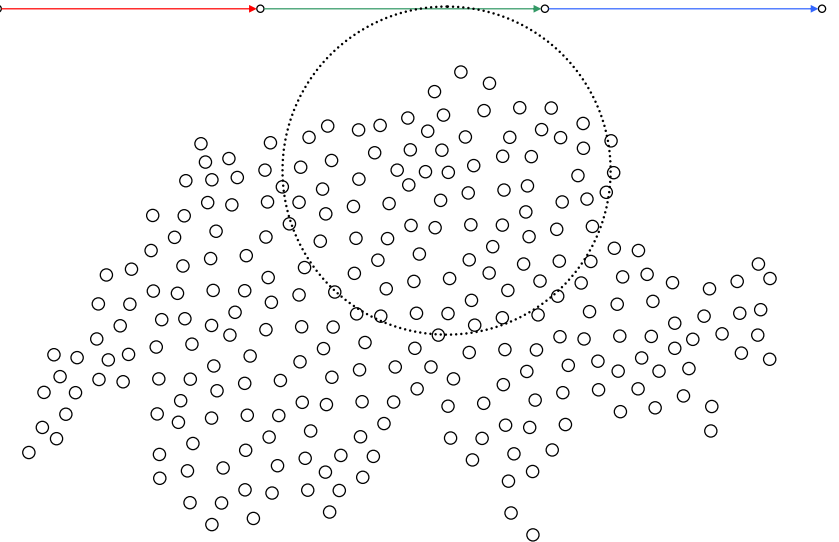
Discussion

- We have seen: **10 Tricks** → 2^{10} routing algorithms
- In reality there are almost that many!

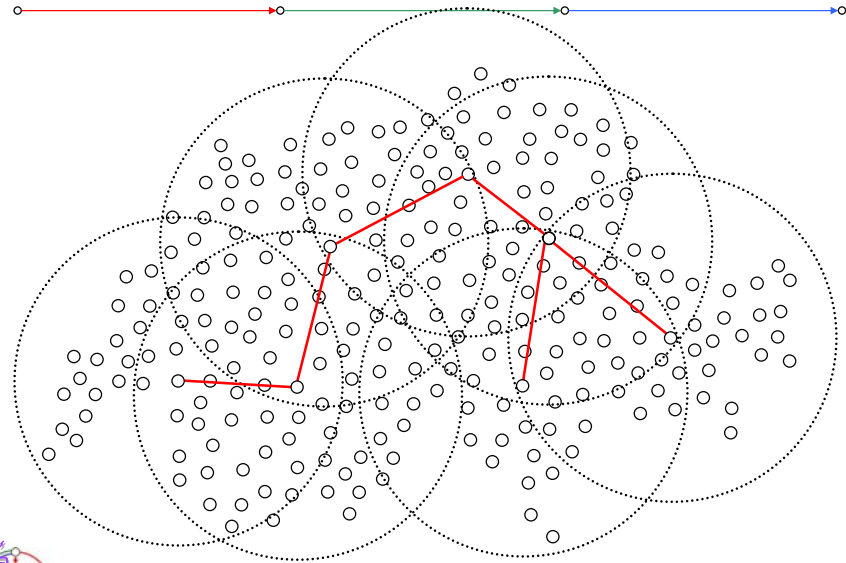
- Q: How good are these routing algorithms?!? **Any hard results?**
- A: Almost none! Method-of-choice is simulation...
- Perkins: “if you simulate three times, you get three different results”

- **Flooding** is key component of (many) proposed algorithms, including most prominent ones (AODV, DSR)
- At least flooding should be efficient

Finding a Destination by Flooding

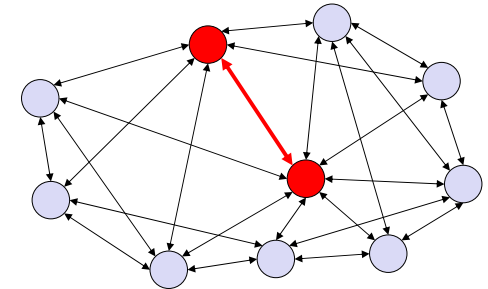


Finding a Destination Efficiently



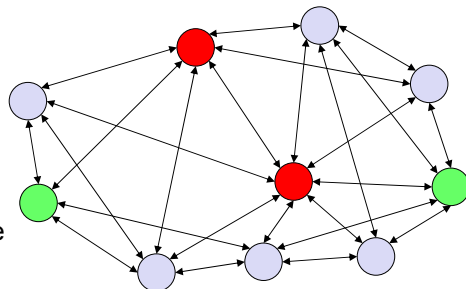
Backbone

- Idea: Some nodes become backbone nodes (gateways). Each node can access and be accessed by at least one backbone node.
- Routing:
 - If source is not a gateway, transmit message to gateway
 - Gateway acts as proxy source and routes message on backbone to gateway of destination.
 - Transmission gateway to destination.



(Connected) Dominating Set

- A **Dominating Set DS** is a subset of nodes such that each node is either in DS or has a neighbor in DS.
- A **Connected Dominating Set CDS** is a connected DS, that is, there is a path between any two nodes in CDS that does not use nodes that are not in CDS.
- A CDS is a good choice for a backbone.
- It might be favorable to have few nodes in the CDS. This is known as the Minimum CDS problem



Formal Problem Definition: M(C)DS

- Input:** We are given an (arbitrary) undirected graph.
- Output:** Find a Minimum (Connected) Dominating Set, that is, a (C)DS with a minimum number of nodes.
- Problems
 - M(C)DS is **NP-hard**
 - Find a (C)DS that is "close" to minimum (**approximation**)
 - The solution must be **local** (global solutions are impractical for mobile ad-hoc network) – topology of graph "far away" should not influence decision who belongs to (C)DS



Greedy Algorithm for Dominating Sets

- Idea: Greedy choose “good” nodes into the dominating set.
- Black nodes are in the DS
- Grey nodes are neighbors of nodes in the CDS
- White nodes are not yet dominated, initially all nodes are white.
- Algorithm: Greedily choose a node that colors most white nodes.
- One can show that this gives a $\log \Delta$ approximation, if Δ is the maximum node degree of the graph. (The proof is similar to the “Tree Growing” proof on 6/14ff.)
- One can also show that there is no polynomial algorithm with better performance unless $P \approx NP$.



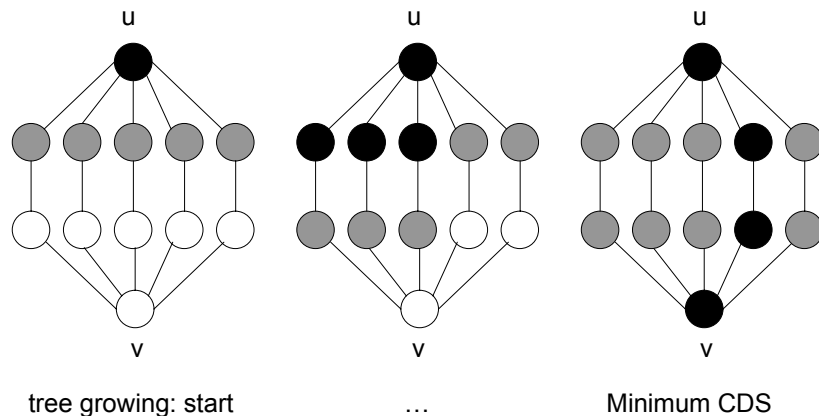
CDS: The “too simple tree growing” algorithm

- Idea: start with the root, and then greedily choose a neighbor of the tree that dominates as many as possible new nodes
- Black nodes are in the CDS
- Grey nodes are neighbors of nodes in the CDS
- White nodes are not yet dominated, initially all nodes are white.
- Start: Choose the node a maximum degree, and make it the root of the CDS, that is, color it black (and its white neighbors grey).
- Step: Choose a grey node with a maximum number of white neighbors and color it black (and its white neighbors grey).



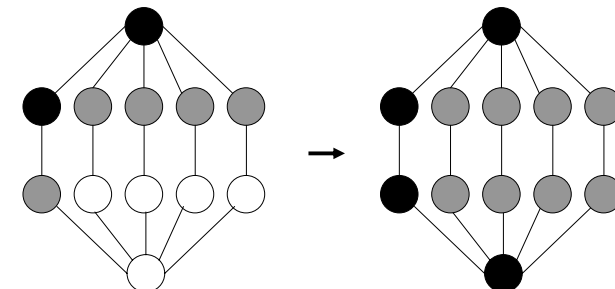
Example of the “too simple tree growing” algorithm

Graph with $2n+2$ nodes; tree growing: $|CDS|=n+2$; Minimum $|CDS|=4$



Tree Growing Algorithm

- Idea: Don't scan one but two nodes!
- Alternative step: Choose a grey node and its white neighbor node with a maximum sum of white neighbors and color both black (and their white neighbors grey).



Analysis of the tree growing algorithm

- Theorem: The tree growing algorithm finds a connected set of size $|CDS| \leq 2(1+H(\Delta)) \cdot |DS_{OPT}|$.
- DS_{OPT} is a (not connected) minimum dominating set
- Δ is the maximum node degree in the graph
- H is the harmonic function with $H(n) \approx \log(n)+0.7$
- In other words, the connected dominating set of the tree growing algorithm is at most a $O(\log(\Delta))$ factor worse than an optimum minimum dominating set (which is NP-hard to compute).
- With a lower bound argument (reduction to set cover) one can show that a better approximation factor is impossible, unless $P \approx NP$.



Proof Sketch

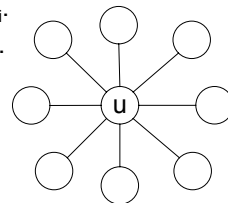
- The proof is done with amortized analysis.
- Let S_u be the set of nodes dominated by $u \in DS_{OPT}$, or u itself. If a node is dominated by more than one node, we put it in one of the sets.
- We charge the nodes in the graph for each node we color black. In particular we charge all the newly colored grey nodes. Since we color a node grey at most once, it is charged at most once.
- We show that the total charge on the vertices in an S_u is at most $2(1+H(\Delta))$, for any u .



Charge on S_u

- Initially $|S_u| = u_0$.
- Whenever we color some nodes of S_u , we call this a step.
- The number of white nodes in S_u after step i is u_i .
- After step k there are no more white nodes in S_u .

- In the first step $u_0 - u_1$ nodes are colored (grey or black). Each vertex gets a charge of at most $2/(u_0 - u_1)$.



- After the first step, node u becomes eligible to be colored (as part of a pair with one of the grey nodes in S_u). If u is not chosen in step i (with a potential to paint u_i nodes grey), then we have found a better (pair of) node. That is, the charge to any of the new grey nodes in step i in S_u is at most $2/u_i$.



Adding up the charges in S_u

$$C \leq \frac{2}{u_0 - u_1} (u_0 - u_1) + \sum_{i=1}^{k-1} \frac{2}{u_i} (u_i - u_{i+1})$$

$$= 2 + 2 \sum_{i=1}^{k-1} \frac{u_i - u_{i+1}}{u_i}$$

$$\leq 2 + 2 \sum_{i=1}^{k-1} (H(u_i) - H(u_{i+1}))$$

$$= 2 + 2(H(u_1) - H(u_k)) = 2(1 + H(u_1)) = 2(1 + H(\Delta))$$



Discussion of the tree growing algorithm

- We have an extremely simple algorithm that is asymptotically optimal unless $P \approx NP$. And even the constants are small.
- Are we happy?
- Not really. How do we implement this algorithm in a real mobile network? How do we figure out where the best grey/white pair of nodes is? How slow is this algorithm in a distributed setting?
- We need a fully distributed algorithm. Nodes should only consider local information.

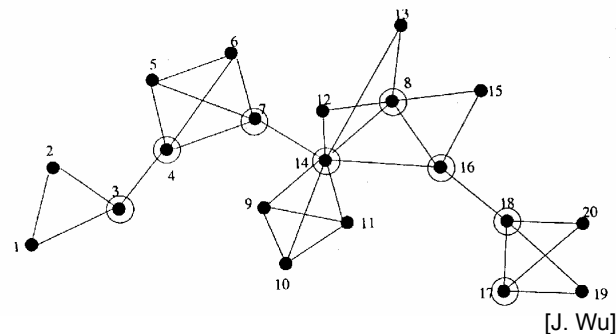


The Marking Algorithm

- Idea: The connected dominating set CDS consists of the nodes that have two neighbors that are not neighboring.
1. Each node u compiles the set of neighbors $N(u)$
 2. Each node u transmits $N(u)$, and receives $N(v)$ from all its neighbors
 3. If node u has two neighbors v, w and w is not in $N(v)$ (and since the graph is undirected v is not in $N(w)$), then u marks itself being in the set CDS.
- + Completely local; only exchange $N(u)$ with all neighbors
 - + Each node sends only 1 message, and receives at most Δ
 - + Messages have size $O(\Delta)$
 - Is the marking algorithm really producing a connected dominating set? How good is the set?



Example for the Marking Algorithm



[J. Wu]

Correctness of Marking Algorithm

- We assume that the input graph G is connected but not complete.
- Note: If G was complete then constructing a CDS would not make sense. Note that in a complete graph, no node would be marked.
- We show:
The set of marked nodes CDS is
 - a) a dominating set
 - b) connected
 - c) a shortest path in G between two nodes of the CDS is in CDS



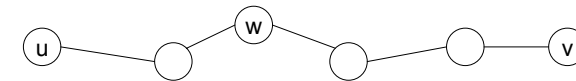
Proof of a) dominating set

- Proof: Assume for the sake of contradiction that node u is a node that is not in the dominating set, and also not dominated. Since no neighbor of u is in the dominating set, the nodes $N^+(u) := u \cup N(u)$ form:
 - a complete graph
 - if there are two nodes in $N(u)$ that are not connected, u must be in the dominating set by definition
 - no node $v \in N(u)$ has a neighbor outside $N(u)$
 - or, also by definition, the node v is in the dominating set
- Since the graph G is connected it only consists of the complete graph $N^+(u)$. We precluded this in the assumptions, therefore we have a contradiction



Proof of b) connected, c) shortest path in CDS

- Proof: Let p be any shortest path between the two nodes u and v , with $u, v \in \text{CDS}$.
- Assume for the sake of contradiction that there is a node w on this shortest path that is not in the connected dominating set.



- Then the two neighbors of w must be connected, which gives us a shorter path. This is a contradiction.



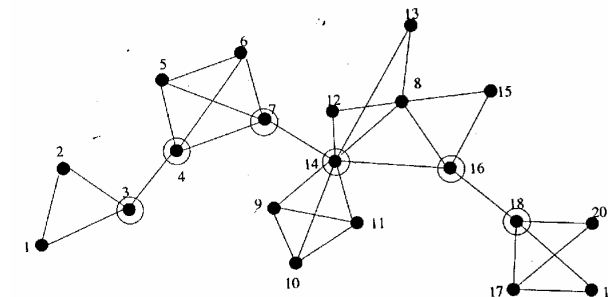
Improving the Marking Algorithm

- We give each node u a unique $\text{id}(u)$.
- Rule 1: If $N^+(v) \subseteq N^+(u)$ and $\text{id}(v) < \text{id}(u)$, then do not include node v into the CDS.
- Rule 2: Let $u, w \in N(v)$. If $N(v) \subseteq N(u) \cup N(w)$ and $\text{id}(v) < \text{id}(u)$ and $\text{id}(v) < \text{id}(w)$, then do not include v into the CDS.
- (Rule 2+: You can do the same with more than 2 covering neighbors, but it gets a little more intricate.)
- ...for a quiet minute: Why are the identifiers necessary?



Example for improved Marking Algorithm

- Node 17 is removed with rule 1
- Node 8 is removed with rule 2

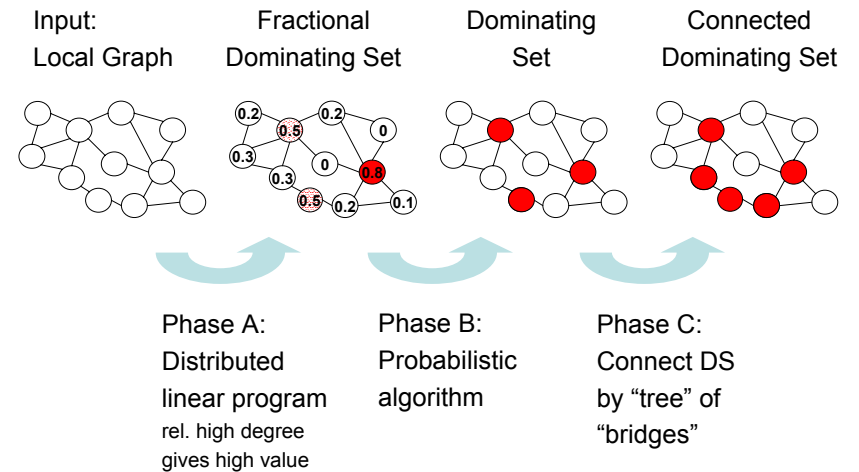


Quality of the Marking Algorithm

- Given an Euclidean chain of n homogeneous nodes
- The transmission range of each node is such that it is connected to the k left and right neighbors, the id's of the nodes are ascending.
- An optimal algorithm (and also the tree growing algorithm) puts every k 'th node into the CDS. Thus $|CDS_{OPT}| \approx n/k$; with $k = n/c$ for some positive constant c we have $|CDS_{OPT}| = O(1)$.
- The marking algorithm (also the improved version) does mark all the nodes (except the k leftmost ones). Thus $|CDS_{Marking}| = n - k$; with $k = n/c$ we have $|CDS_{Marking}| = \Omega(n)$.
- The worst-case quality of the marking algorithm is worst-case! ☹️



The k-local Algorithm



Result of the k-local Algorithm

- Distributed Approximation

$$\text{Theorem: } E[|DS|] \leq O(\alpha \ln \Delta \cdot |DS_{OPT}|)$$

- The value of α depends on the number of rounds k (the locality)

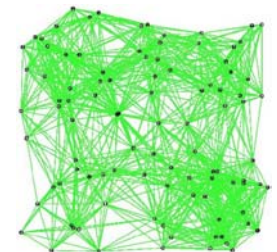
$$\alpha \leq (\Delta + 1)^{5/\sqrt{k}}$$

- The analysis is rather intricate... ☹️



Unit Disk Graph

- We are given a set V of nodes in the plane (points with coordinates).
- The unit disk graph $UDG(V)$ is defined as an undirected graph (with E being a set of undirected edges). There is an edge between two nodes u, v iff the Euclidian distance between u and v is at most 1.
- Think of the unit distance as the maximum transmission range.
- We assume that the unit disk graph UDG is connected (that is, there is a path between each pair of nodes)
- The unit disk graph has many edges.
- Can we drop some edges in the UDG to reduced complexity and interference?

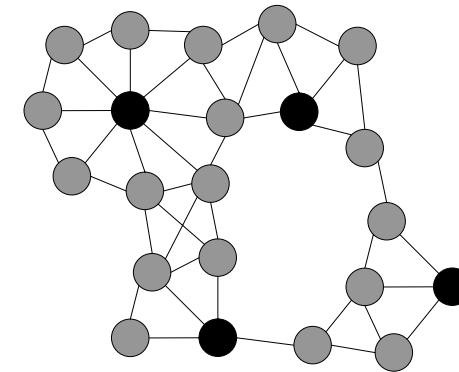


The “Dominator!” Algorithm

- For the important special case of Euclidean Unit Disk Graphs there is a simple marking algorithm that does the job.
- We make the simplifying assumptions that MAC layer issues are resolved: Two nodes u, v within transmission range 1 receive both all their transmissions. There is no interference, that is, the transmissions are locally always completely ordered.
- Initially no node is in the connected dominating set CDS.
 1. If a node u has not yet received an “I AM A DOMINATOR, BABY!” message from any other node, node u will transmit “I AM A DOMINATOR, BABY!”
 2. If node v receives a message “I AM A DOMINATOR, BABY!” from node u , then node v is dominated by node u .



Example



- This gives a dominating set. But it is not connected.



The “Dominator!” Algorithm Continued

3. If a node w is dominated by more two dominators u and v , and node w has not yet received a message “I am dominated by u and v ”, then node w transmits “I am dominated by u and v ” and enters the CDS.
- And since this is still not quite enough...
4. If a neighboring pair of nodes w_1 and w_2 is dominated by dominators u and v , respectively, and have not yet received a message “I am dominated by u and v ”, or “We are dominated by u and v ”, then nodes w_1 and w_2 both transmit “We are dominated by u and v ” and enter the CDS.



“Dominator Algorithm”: Results

- The “Dominator!” Algorithm produces a connected dominating set.
- The algorithm is completely local. (is it?)
- Each node only has to transmit one or two messages of constant size.
- The connected dominating set is asymptotically optimal, that is, $|CDS| = O(|CDS_{OPT}|)$.
- Routes on backbone (CDS) are only by a constant factor longer than on UDG.



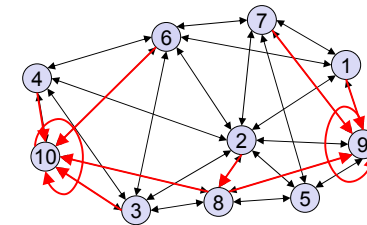
“Dominator Algorithm”: Remarks

- “Dominator” algorithm seems to be very local.
- If two neighbors want to join the DS simultaneously, we have a problem → synchronization between nodes is a problem!
- Algorithm actually calculates a maximal independent set (MIS).
- When taking care of all synchronization problems, best known MIS algorithm needs time $O(\log n)$.
- Lower Bound for general graphs: $\Omega\left(\sqrt{\frac{\log n}{\log \log n}}\right)$
- If you want to know more, visit PODC course!



The “Largest-ID” Algorithm

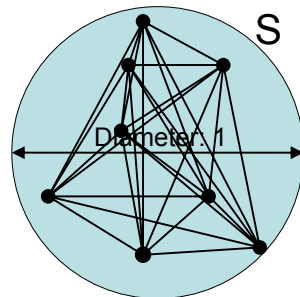
- All nodes have unique IDs
- Algorithm for each node:
 1. Send ID to all neighbors
 2. Tell node with largest ID in neighborhood that it has to join the DS
- Algorithm computes a DS in 2 rounds (extremely local!)



“Largest ID” Algorithm, Analysis I

- Assume, node IDs are at random, graph is UDG.
- We look at a disk S of diameter 1:

Nodes inside S have distance at most 1.
→ they form a clique

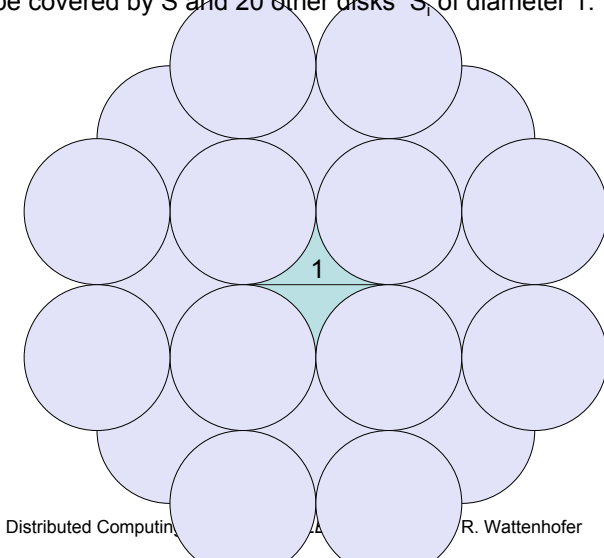


How many nodes in S are selected for the DS?



“Largest ID” Algorithm, Analysis II

- Nodes which select nodes in S are in disk of radius $3/2$ which can be covered by S and 20 other disks S_i of diameter 1.



“Largest ID” Algorithm: Analysis III

- How many nodes in S are chosen by nodes in a disk S_i ?
- $x = \#$ of nodes in S, $y = \#$ of nodes in S_i :
- A node $u \in S$ is only chosen by a node in S_i if $\text{ID}(u) > \max_{v \in S_i} \{\text{ID}(v)\}$ (all nodes in S_i see each other).
- The probability for this is: $\frac{1}{1+y}$
- Therefore, the expected number of nodes in S chosen by nodes in S_i is at most:

$$\min \left\{ y, \frac{x}{1+y} \right\}$$

Because at most y nodes in S_i can choose nodes in S and because of linearity of expectation.



“Largest ID” Algorithm, Analysis IV

- From $x \leq n$ and $y \leq n$, it follows that: $\min \left\{ y, \frac{x}{1+y} \right\} \leq \sqrt{n}$
- Hence, in expectation the DS contains at most $20\sqrt{n}$ nodes per disk with diameter 1.
- An optimal algorithm needs to choose at least 1 node in the disk with radius 1 around any node.
- This disk can be covered by a constant (9) number of disks of diameter 1.
- The algorithm chooses at most $O(\sqrt{n})$ times more disks than an optimal one



“Largest ID” Algorithm, Remarks

- For typical settings, the “Largest ID” algorithm produces very good dominating sets (also for non-UDGs)
- There are UDGs where the “Largest ID” algorithm computes an $\Theta(\sqrt{n})$ -approximation (analysis is tight).
- If nodes know the distances to each other, there is a iterative variant of the “Largest ID” algorithm which computes a constant approximation in $O(\log \log n)$ time.



Overview of (C)DS Algorithms

Algorithm	Worst-Case Guarantees	Local (Distributed)	General Graphs	CDS
Greedy	Yes, optimal unless P=NP	No	Yes	No
Tree Growing	Yes, optimal unless P=NP	No	Yes	Yes
Marking	No	Yes (const.)	Yes	Yes
k-local	Yes, but with add. factor α	Yes (k-local)	Yes	Yes
“Dominators!”	Asymptotically Optimal	Yes (log n)	No	Yes
“Largest ID” simple / iter.	$O(\sqrt{n})$ / constant	Yes (const / loglog n)	No	Yes

