

DYNAMO

 $\mathrm{HS}\ 2023$

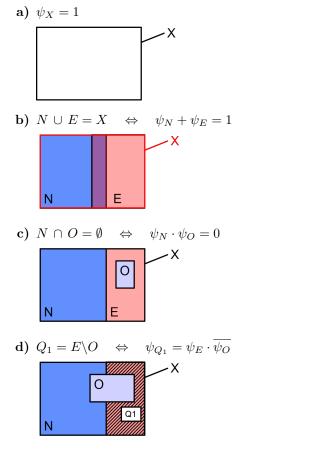
Prof. Dr. Lana Josipović and Jiahui Xu based on Prof. Lothar Thiele's material

Discrete Event Systems

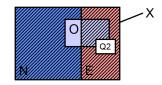
Solution to Exercise Sheet 11

1 Set Representation

1.1 Warm-up



e) $Q_2 = (O \cap E) \cup \overline{O} = (O \cup \overline{O}) \cap (E \cup \overline{O}) \iff \psi_{Q_2} = \psi_E + \overline{\psi_O}$ = $X \cap (E \cup \overline{O})$ = $E \cup \overline{O}$



1.2 Specification Composition

- a) The specification for $\mathbf{C1},\,\mathbf{C2}$ and $\mathbf{C3}$ are the following:
 - **C1** $\psi_{C1} = (x_1 + x_2 + x_3) \to x_s$
 - $\psi_{C1} = (x_1 + x_2 + x_3)x_s + \overline{x_1} \cdot \overline{x_2} \cdot \overline{x_3} = x_s + \overline{x_1} \cdot \overline{x_2} \cdot \overline{x_3}$
 - **C2** $\psi_{C2} = x_1 \cdot \overline{x_2} \cdot \overline{x_3} + \overline{x_1} \cdot x_2 \cdot \overline{x_3} + \overline{x_1} \cdot \overline{x_2} \cdot x_3 + \overline{x_1} \cdot \overline{x_2} \cdot \overline{x_3}$
 - C3 $\psi_{C3} = x_b \rightarrow (x_s \cdot \overline{x_1} \cdot \overline{x_2} \cdot \overline{x_3})$ $\psi_{C3} = x_b \cdot x_s \cdot \overline{x_1} \cdot \overline{x_2} \cdot \overline{x_3} + \overline{x_b} = x_s \cdot \overline{x_1} \cdot \overline{x_2} \cdot \overline{x_3} + \overline{x_b}$
- b) The specification consists in satisfying all constraints at all times:

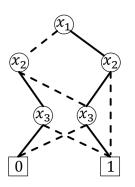
 $\psi_N = \psi_{C1} \cdot \psi_{C2} \cdot \psi_{C3}$

2 Binary Decision Diagrams

2.1 Verification using BDDs

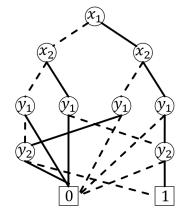
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a) f_2: y = \overline{\overline{x_1 + x_2 + x_3}} + \overline{\overline{x_1 + \overline{x_2} + \overline{x_3}}} + \overline{\overline{x_1 + \overline{x_2} + x_3}}
b) for f_1, we have
                                                                                                 for f_2, we have
       • case x_1 = 0:
                                                                                                  • case x_1 = 0:
                                                                                                      y_{|x_1=0} = \overline{x_2 + x_3} + \overline{\overline{x_2} + \overline{x_3}}
           y_{|x_1=0} = \overline{x_2}x_3 + x_2\overline{x_3}
            - \operatorname{case} x_2 = 0:
                                                                                                      - \operatorname{case} x_2 = 0:
                                                                                                          y_{|x_1=0,x_2=0} = \overline{\overline{x_3} + \overline{1 + \overline{x_3}}} = x_3
                y_{|x_1=0,x_2=0} = x_3
            - \operatorname{case} x_2 = 1:
                                                                                                      - \operatorname{case} x_2 = 1:
                                                                                                          y_{|x_1=0,x_2=1} = \overline{1} + \overline{\overline{x_3}} = \overline{x_3}
                y_{|x_1=0,x_2=1} = \overline{x_3}
       • case x_1 = 1:
                                                                                                  • case x_1 = 1:
                                                                                                      y_{|x_1=1} = \overline{1} + \overline{1} + \overline{\overline{x_2} + x_3} = \overline{x_2} + x_3
           y_{|x_1=1} = \overline{x_2} + x_3 + \overline{x_2}x_3
                                                                                                      - case x_2 = 0:
            - \operatorname{case} x_2 = 0:
                                                                                                           y_{|x_1=1,x_2=0} = 1
                y_{|x_1=1,x_2=0} = 1
                                                                                                      - \operatorname{case} x_2 = 1:
           - \operatorname{case} x_2 = 1:
                y_{|x_1=1,x_2=1} = x_3
                                                                                                           y_{|x_1=1,x_2=1} = x_3
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The two ROBDDs have identical falls, therefore they are equivalent.



2.2 BDDs with Respect to Different Orderings

- $\mathbf{a)} \ g = x_1 \Big\{ x_2 \big[y_1(y_2) + \overline{y_1}(0) \big] + \overline{x_2} [y_1(\overline{y_2}) + \overline{y_1}(0)] \Big\} + \overline{x_1} \Big\{ x_2 \big[y_1(0) + \overline{y_1}(y_2) \big] + \overline{x_2} \big[y_1(0) + \overline{y_1}(\overline{y_2}) \big] \Big\}$
- **b)** The ROBDD for g is the following:



c) Using the new ordering π' , the Boole-Shannon decomposition becomes

$$g = x_1 \Big\{ y_1 \big[x_2(y_2) + \overline{x_2}(\overline{y_2}) \big] + \overline{y_1}[0] \Big\} + \overline{x_1} \Big\{ y_1[0] + \overline{y_1} \big[x_2(y_2) + \overline{x_2}(\overline{y_2}) \big] \Big\}.$$

This is a better ordering as it leads to a ROBDD with fewer nodes with respect to π (6 instead of 9).

