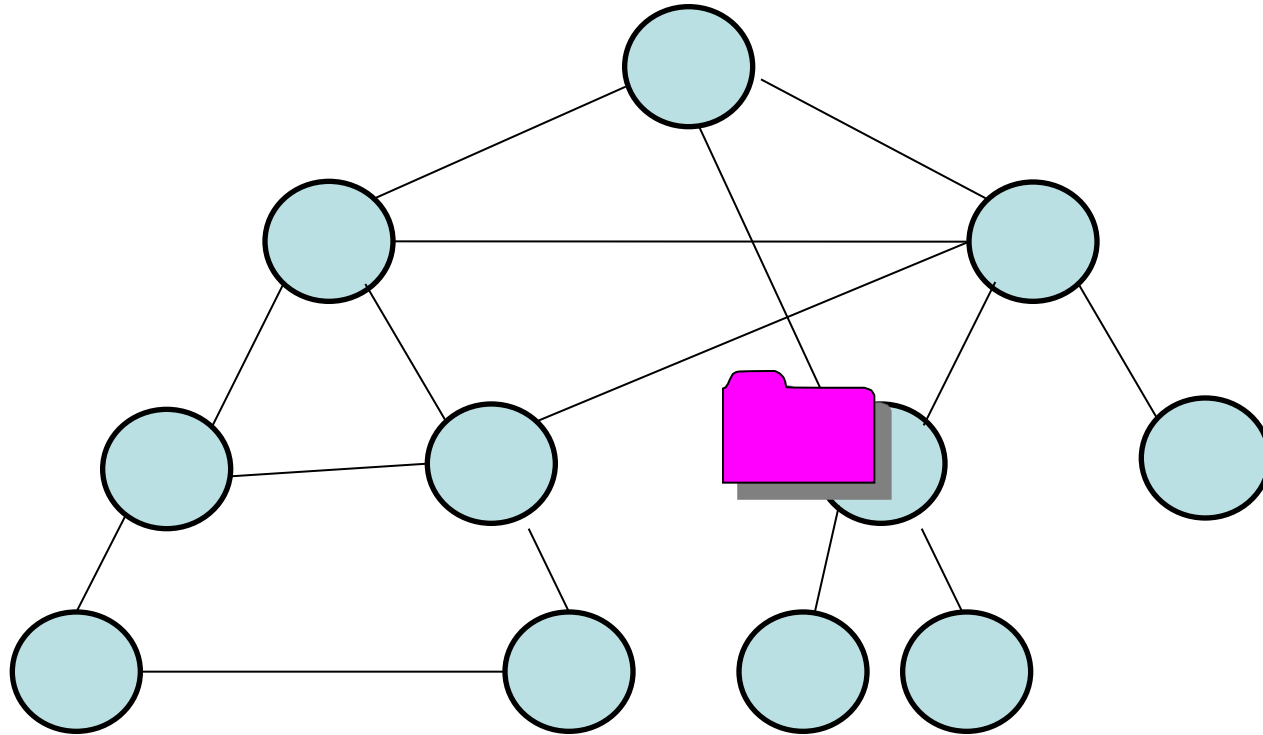


Network Algorithms

Mutual Exclusion in Networks

Shared Objects

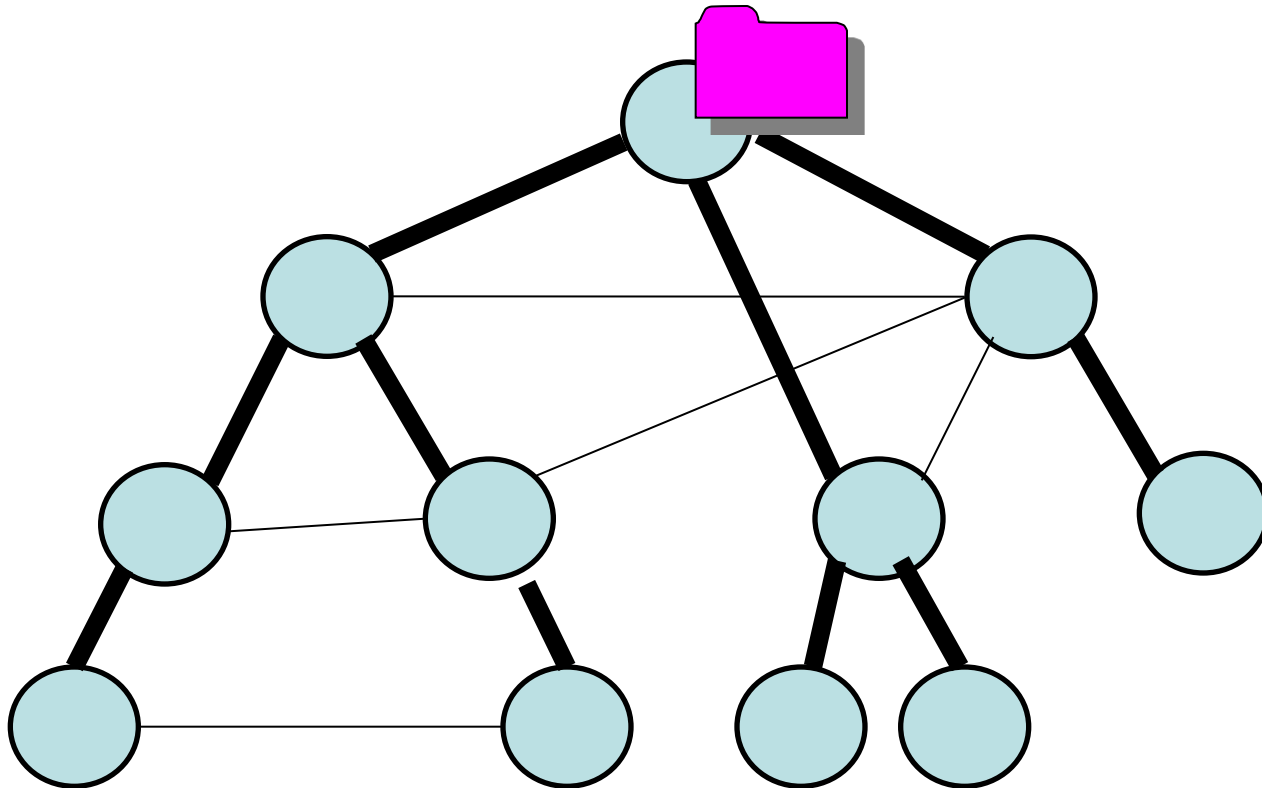
Common variable or datastructure:



Needs to be accessed, but **not concurrently!** How?

Shared Objects

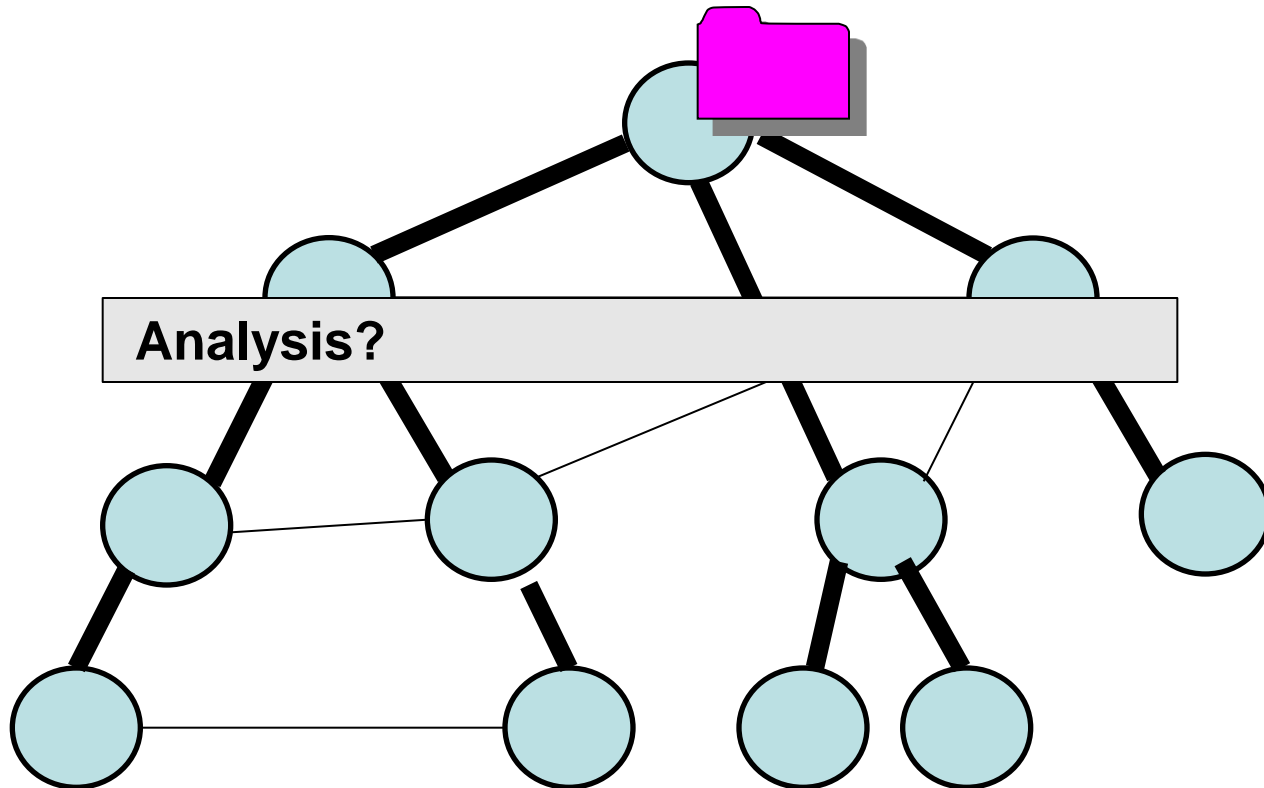
Idea: store at central location, e.g., root of spanning tree



Access: send message to root, root processes request, result sent back down the tree.

Shared Objects

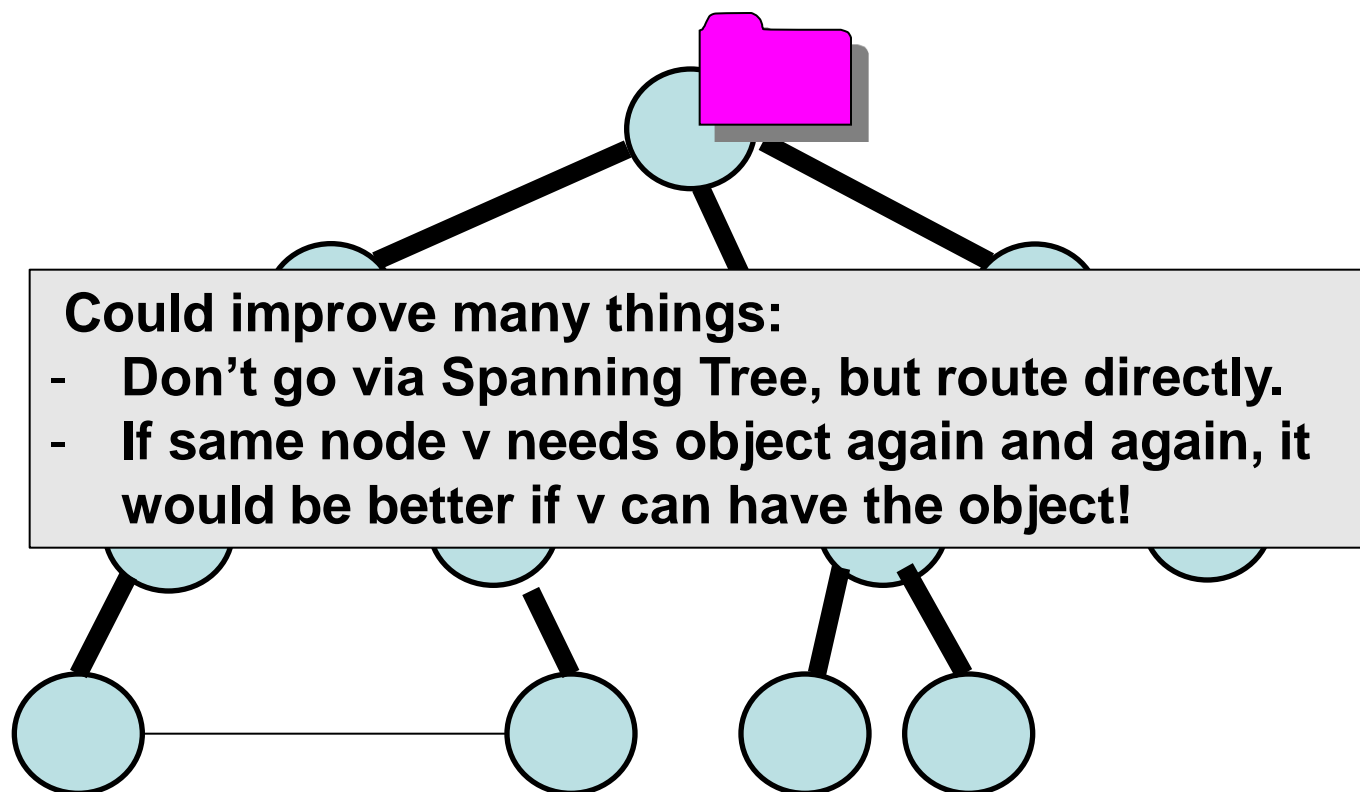
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Shared Objects

Idea: store at central location, e.g., root of spanning tree



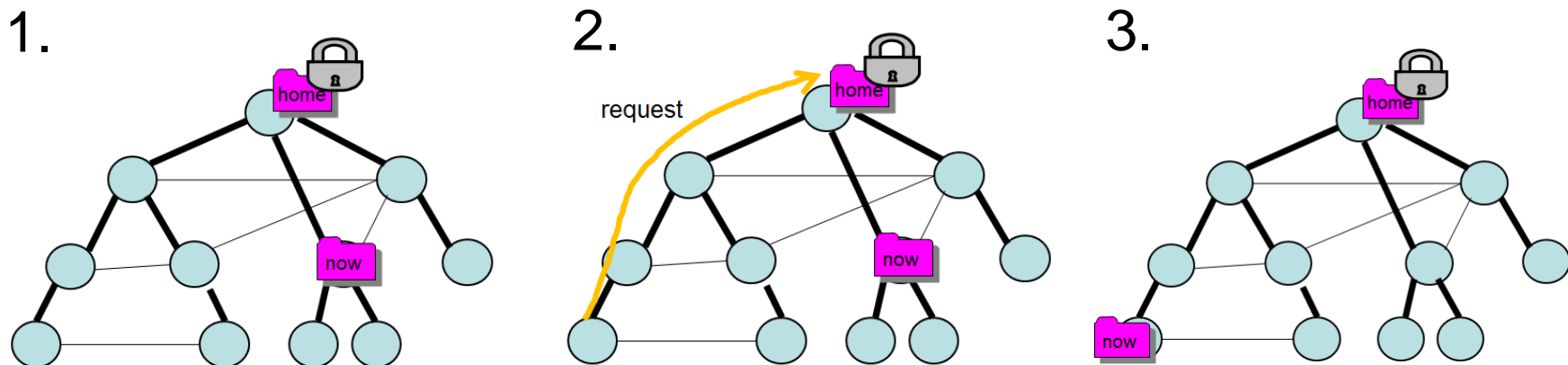
Access: send message to root, root processes request, result sent back down the tree.

Home-Based Solution

Idea that object has «**home base**»:

- processes get **lock** from there
- then retrieve object and process locally!

Similar to Mobile IP!



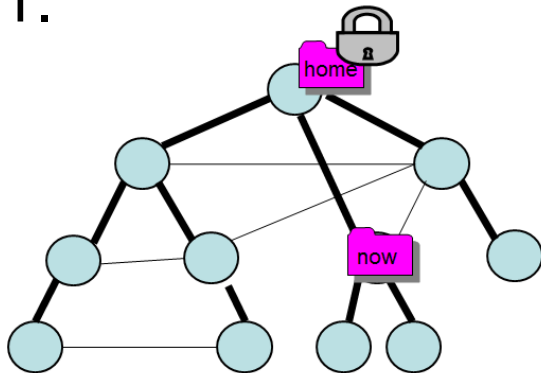
Home-Based Solution

Idea that object has «**home base**»:

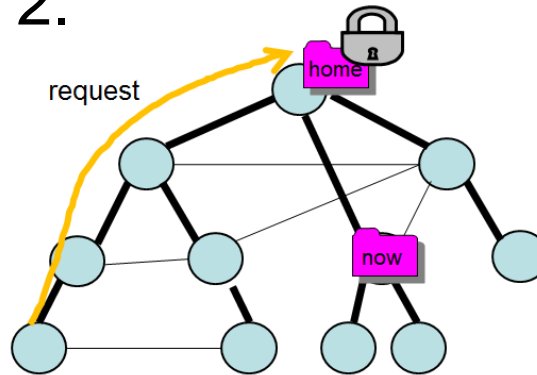
- processes get **lock** from there
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Similar to Mobile IP!

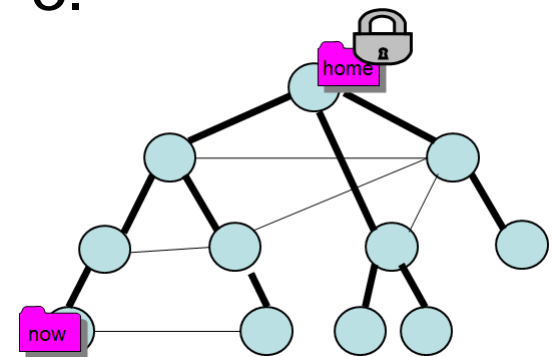
1.



2.



3.



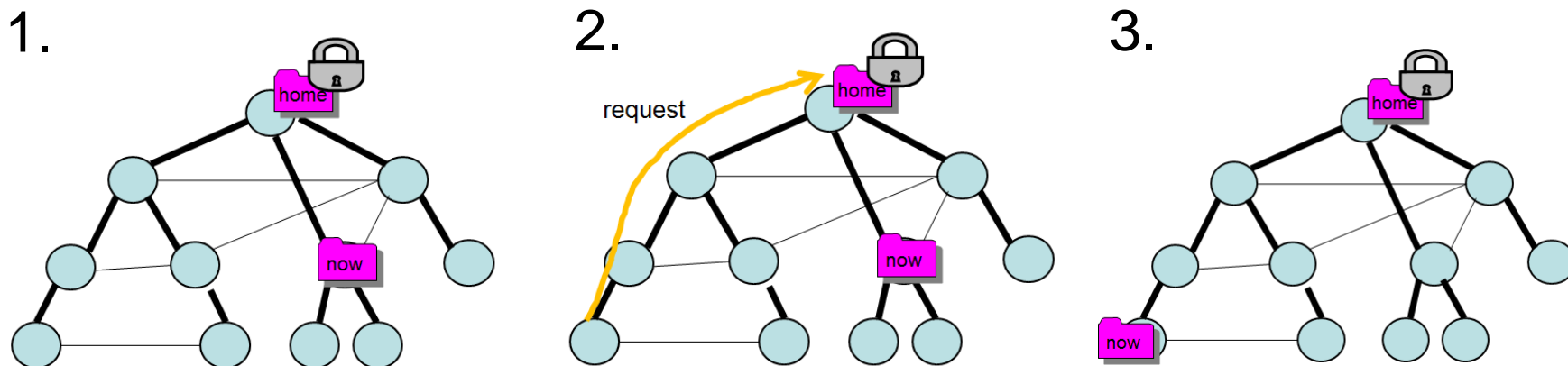
Problem?

Home-Based Solution

Idea that object has «**home base**»:

- processes get **lock** from there
- then retrieve object and process locally!

Similar to Mobile IP!



Problem?

Triangle Routing if accessing nodes are close but root is far.

The Arrow Protocol

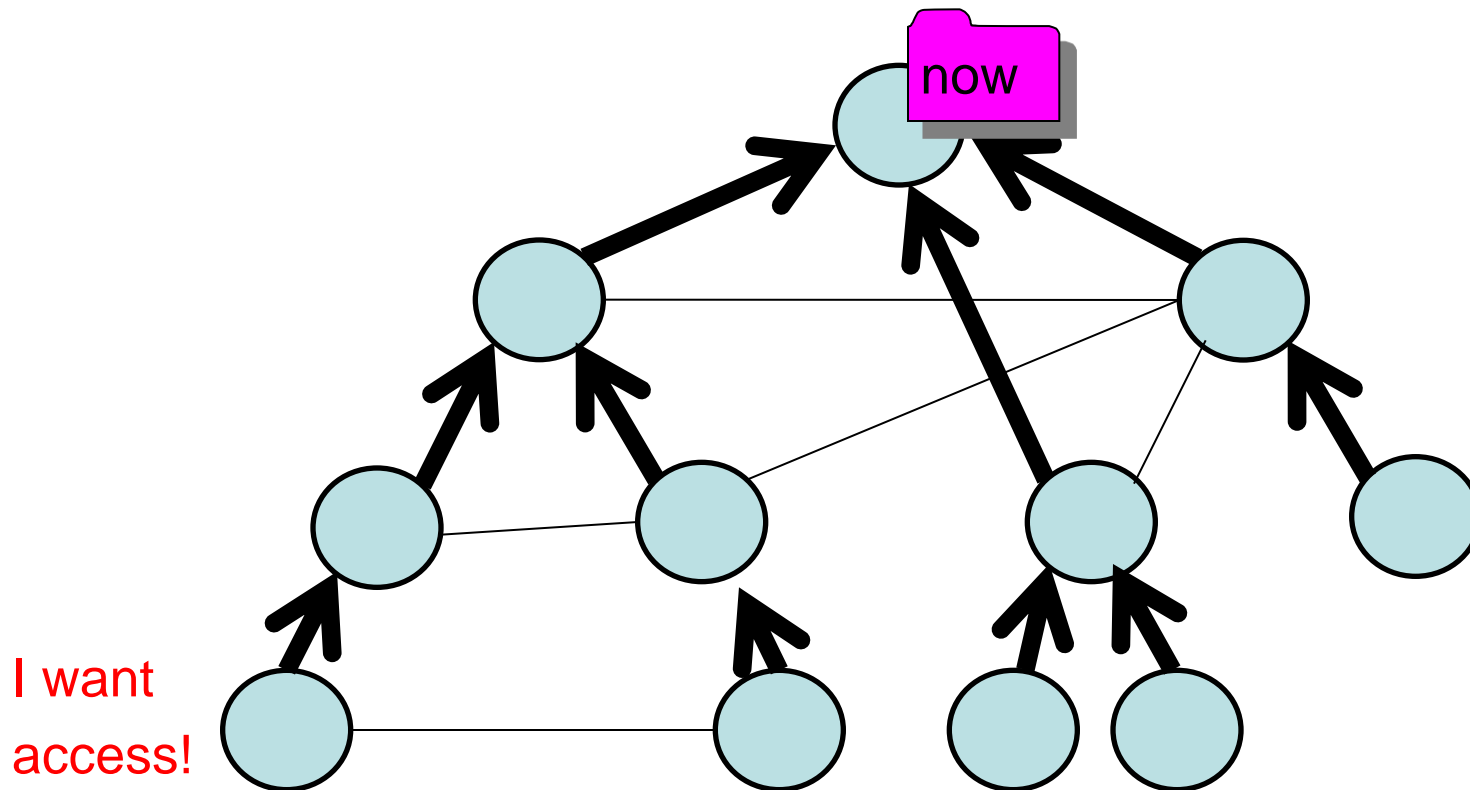
Idea: Make accessor responsible for object, i.e. the new «root».

How can this be achieved?

The Arrow Protocol

Idea: Make accessor responsible for object, i.e. the new «root».

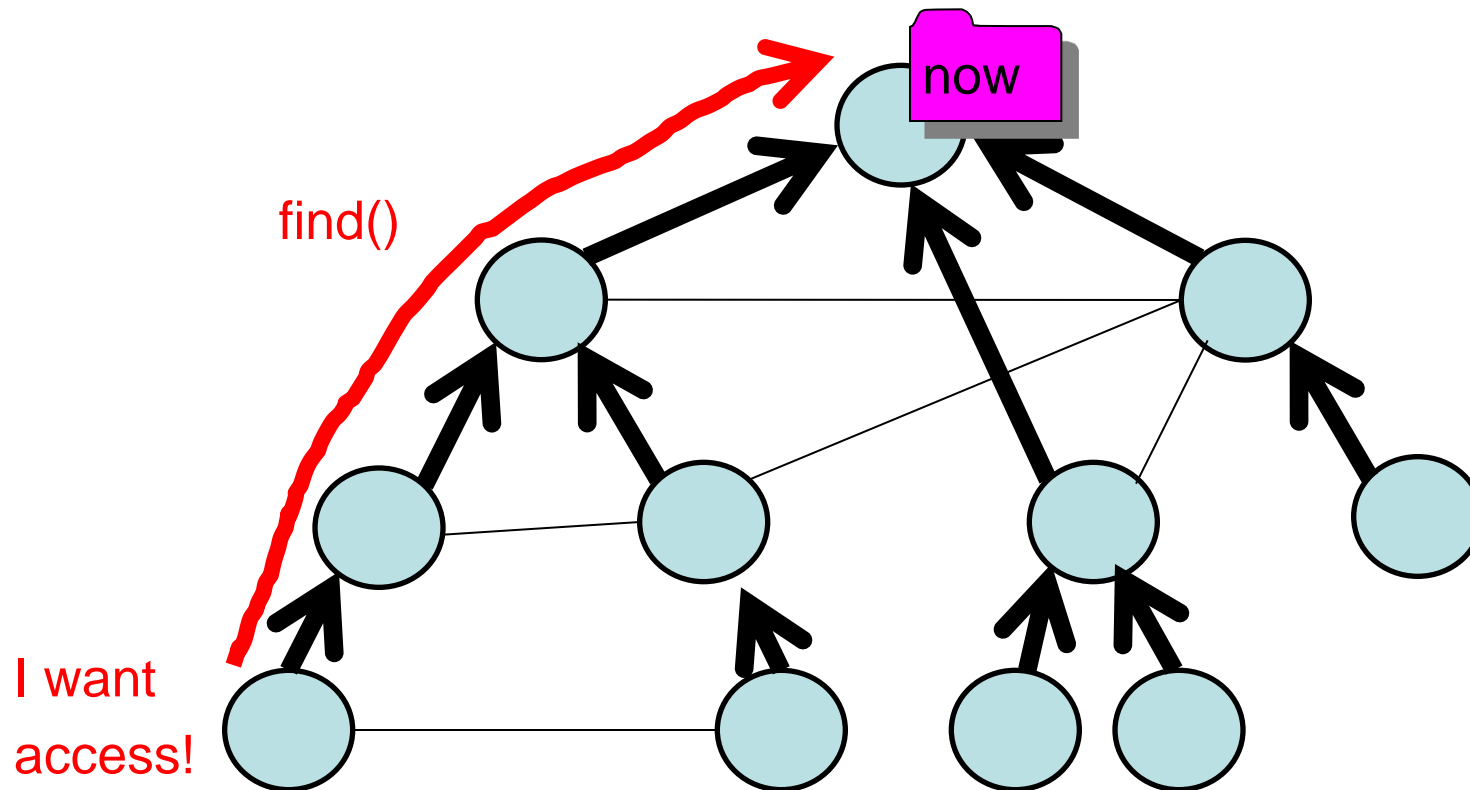
(1) Make tree directed



The Arrow Protocol

Idea: Make accessor responsible for object, i.e. the new «root».

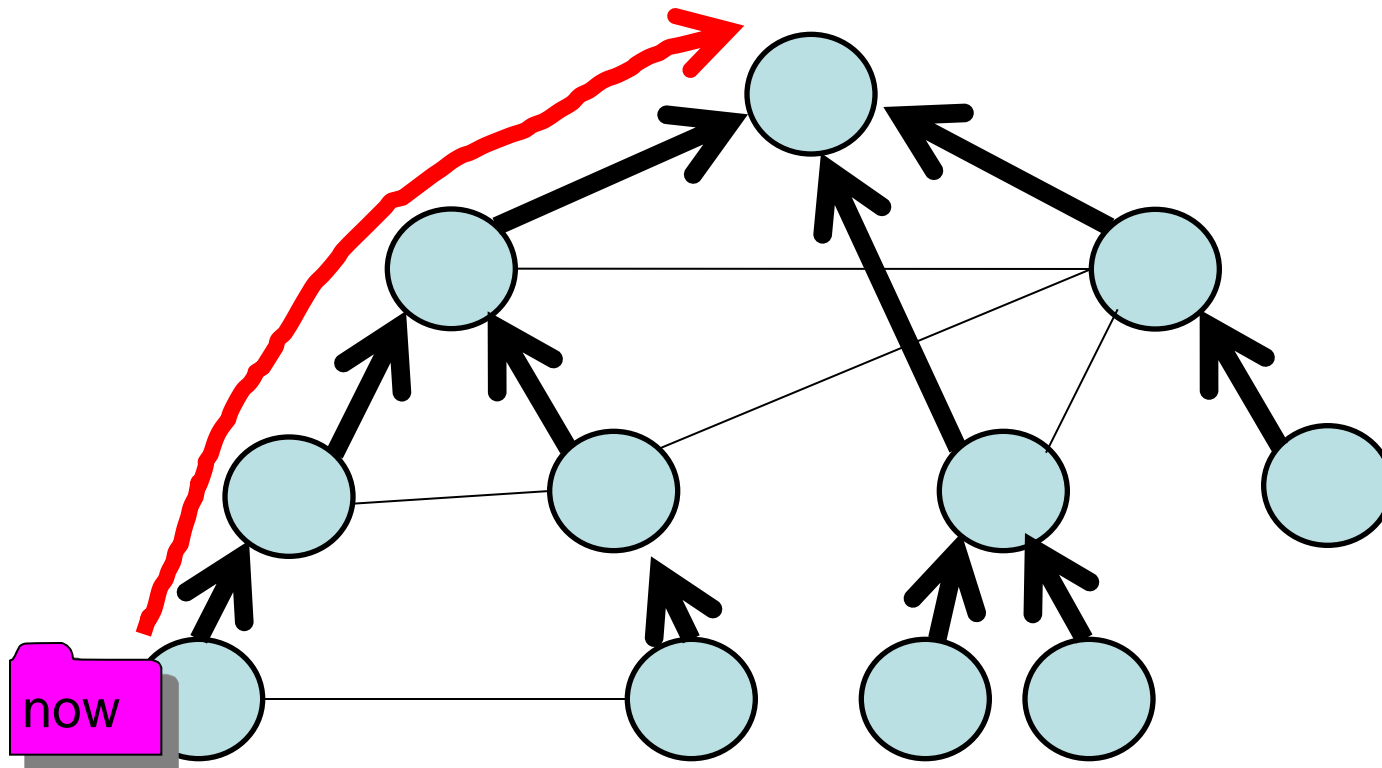
(1) Make tree directed



The Arrow Protocol

Idea: Make accessor responsible for object, i.e. the new «root».

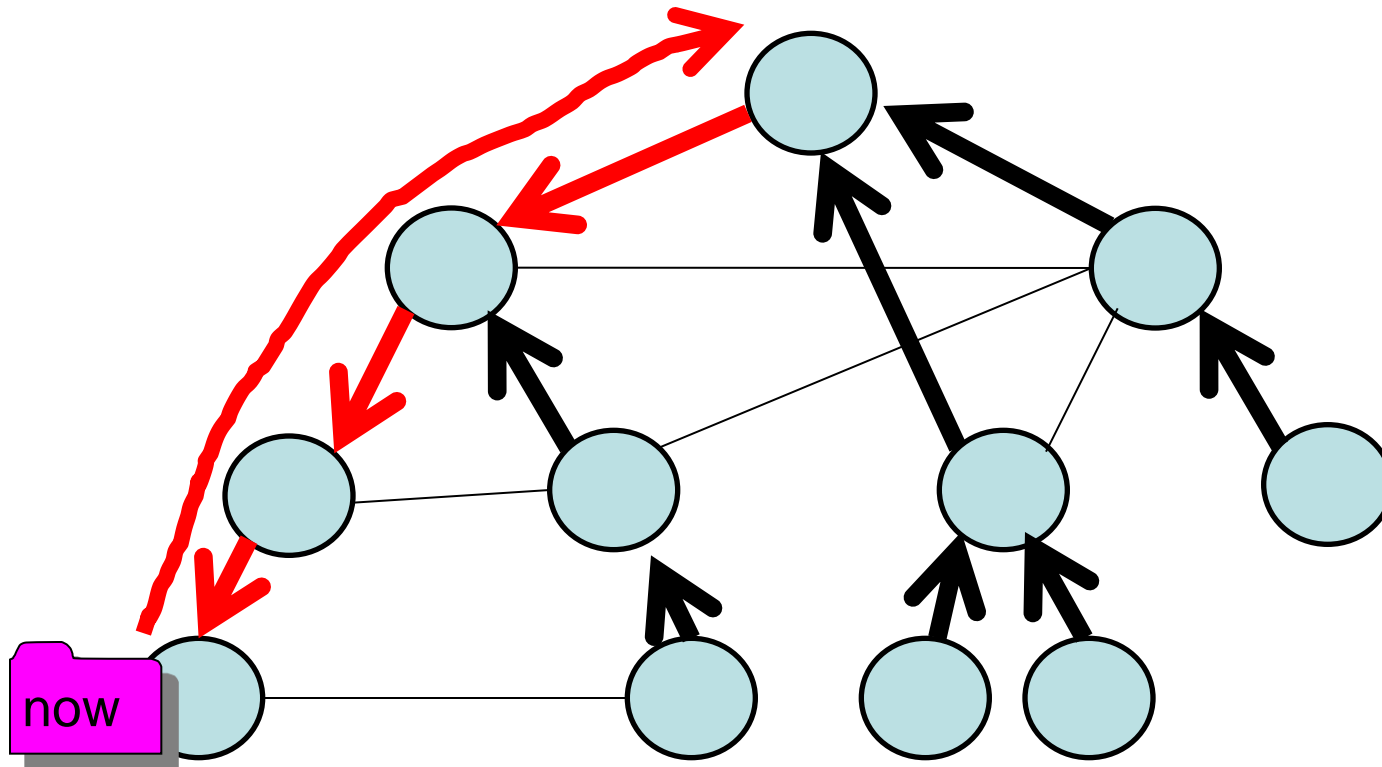
- (1) Make tree directed
- (2) Give object to accessor, new root!



The Arrow Protocol

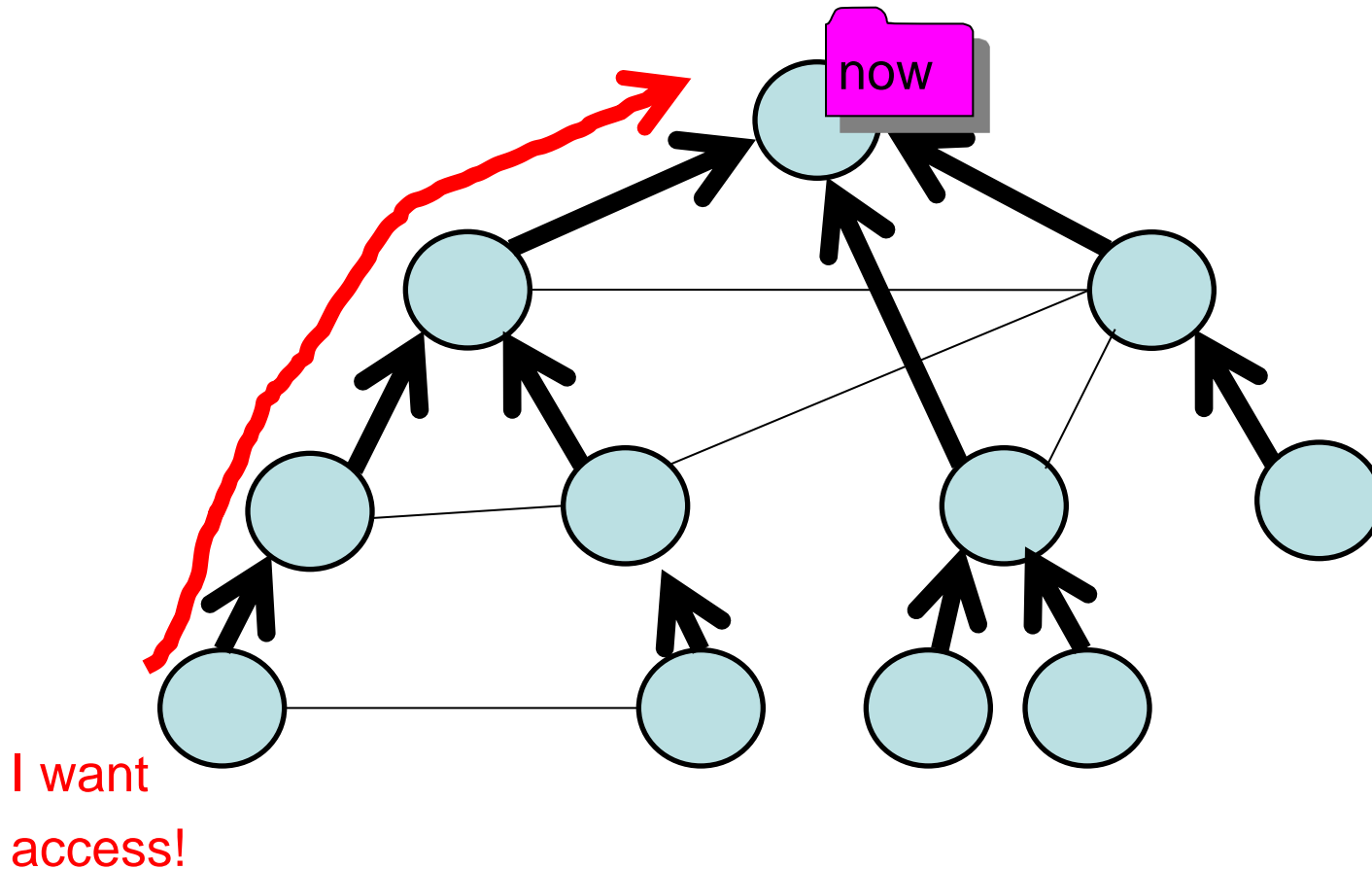
Idea: Make accessor responsible for object, i.e. the new «root».

- (1) Make tree directed
- (2) Give object to accessor, new root!
- (3) Invert pointers along the find path in spanning tree!

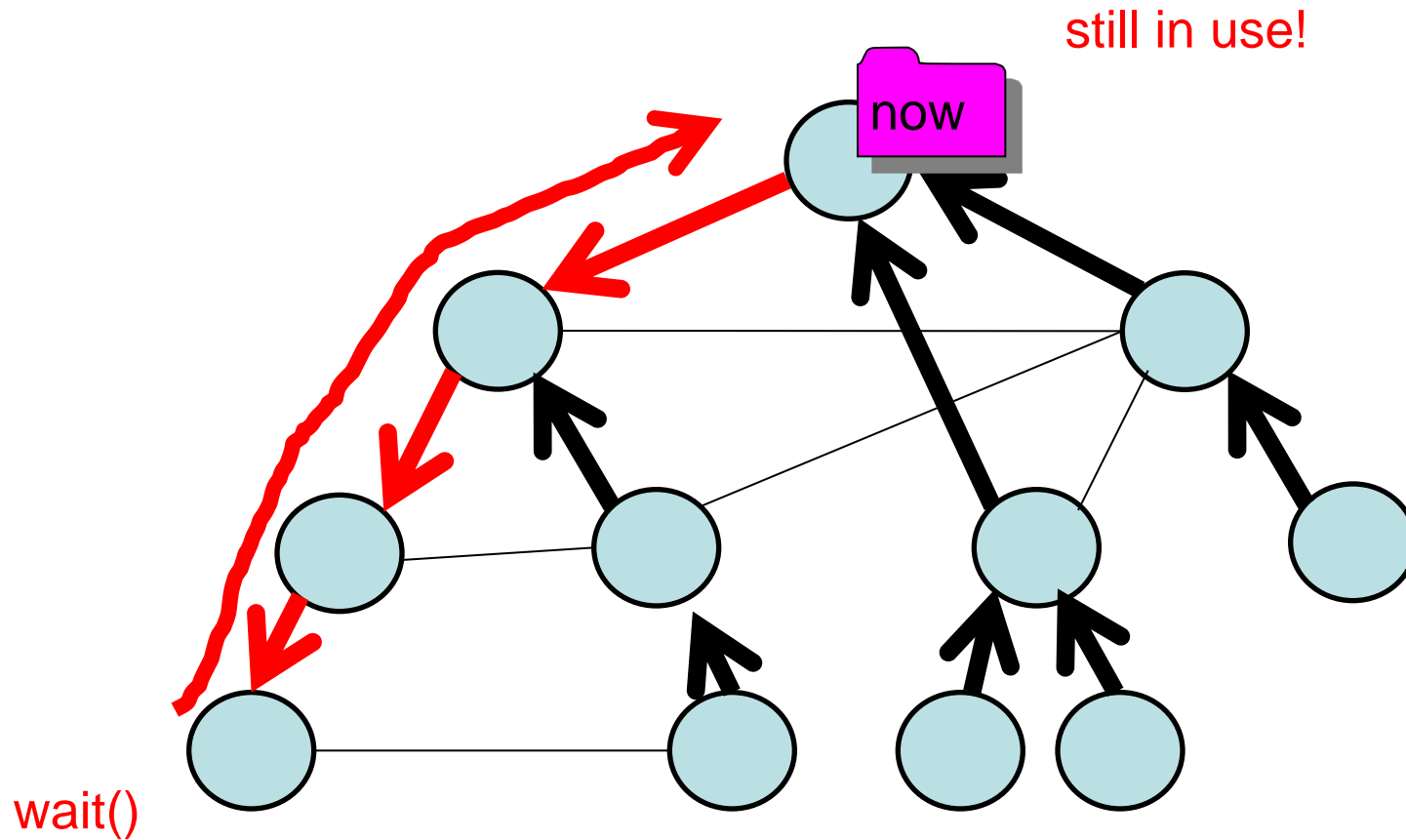


Arrow: What about concurrency?

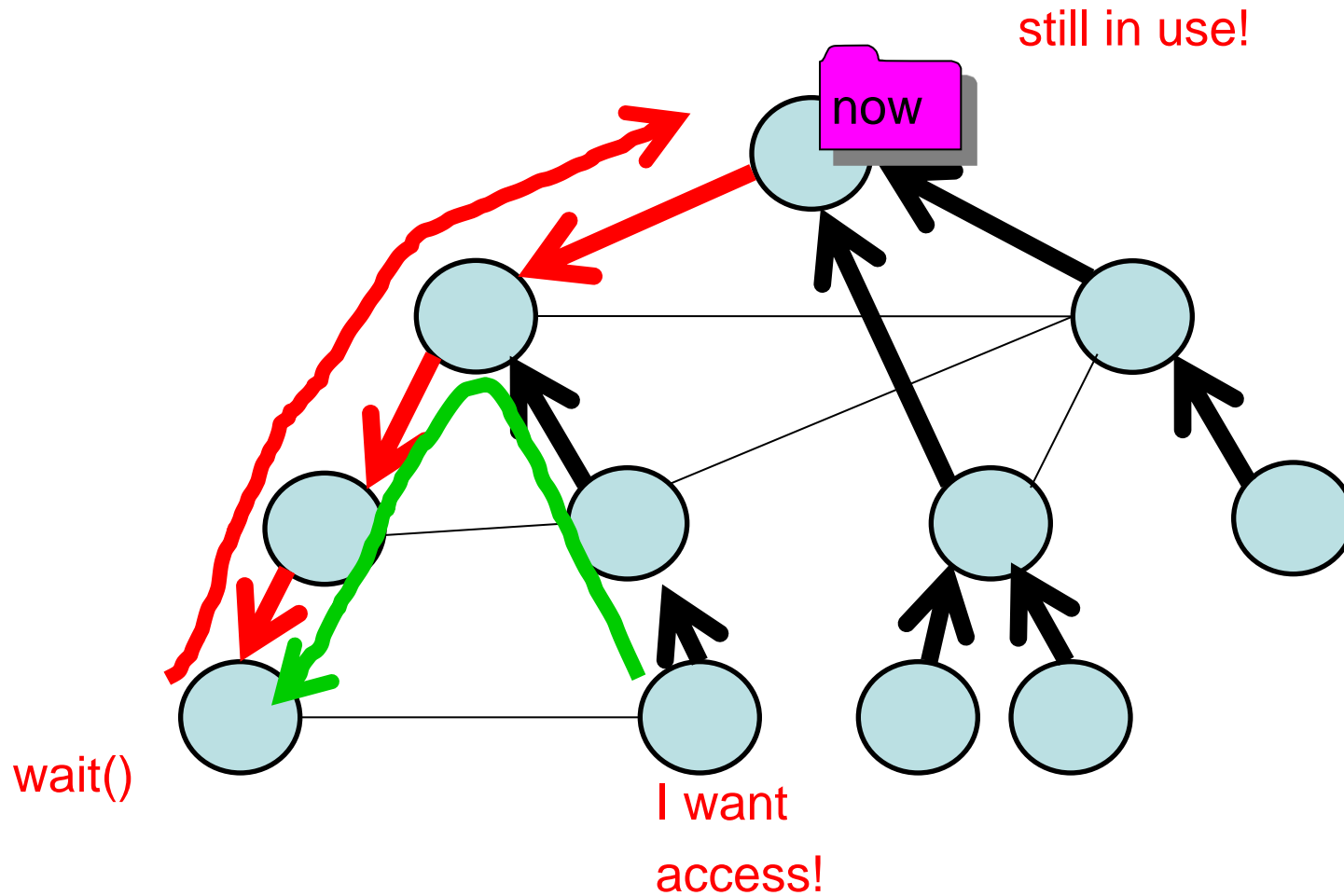
Arrow: What about concurrency?



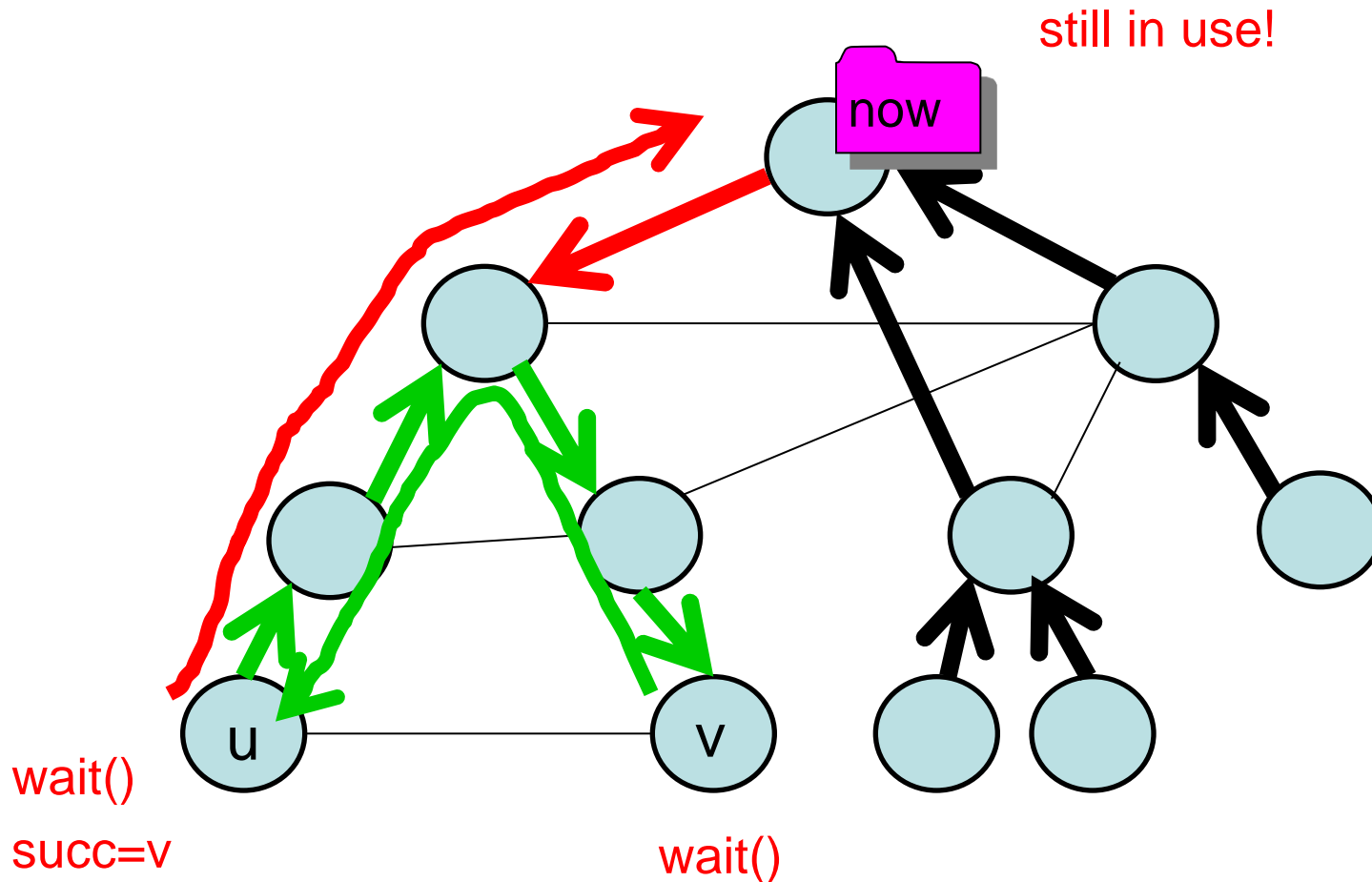
Arrow: What about concurrency?



Arrow: What about concurrency?



Arrow: What about concurrency?



Perfect: tree automatically rooted at node v now! Distributed queue.
Node u can just send it directly to v («out-of-band») when done.

Arrow

Start Find Request at Node u :

- 1: **do atomically**
- 2: u sends “find by u ” message to parent node
- 3: $u.parent := u$
- 4: $u.wait := \mathbf{true}$
- 5: **end do**

Upon w Receiving “Find by u ” Message from Node v :

- 6: **do atomically**
- 7: **if** $w.parent \neq w$ **then**
- 8: w sends “find by u ” message to parent
- 9: $w.parent := v$
- 10: **else**
- 11: $w.parent := v$ **invert edge!**
- 12: **if not** $w.wait$ **then**
- 13: send variable to u // w holds var. but does not need it any more
- 14: **else**
- 15: $w.successor := u$ // w will send variable to u a.s.a.p.
- 16: **end if**
- 17: **end if** **wait myself?**
- 18: **end do**

Upon w Receiving Shared Object:

- 19: perform operation on shared object
- 20: **do atomically**
- 21: $w.wait := \mathbf{false}$
- 22: **if** $w.successor \neq \mathbf{null}$ **then**
- 23: send variable to $w.successor$
- 24: $w.successor := \mathbf{null}$
- 25: **end if**
- 26: **end do**

Arrow

Arrow is correct: find() terminates with message and time complexity D , where D is the diameter of the spanning tree. Completely **asynchronous and concurrent** environments!

Proof.

- Each edge $\{u,v\}$ in the spanning tree is in one of four states:
 - (A) u points to v , no message on the edge, v does not point to u
 - (B) Message on the move from u to v (no pointer along edge)
 - (C) v points to u , no message on edge, u does not point to v
 - (D) Message on the move from v to u (no pointer along edge)
- So message will only travel on static tree!
- And can never traverse an edge twice (in opposite direction).

QED

End of Lecture
