



# Discrete Event Systems

## Solution to Exercise Sheet 13

### 1 Network Calculus

Recall that  $\alpha$  fulfills the arrival curve property if

$$\forall t \forall s : R(t) - R(s) \leq \alpha(t - s) ,$$

and  $\beta$  is a service curve if

$$\forall t \exists s : R^*(t) - R(s) \geq \beta(t - s) .$$

a) If  $R \leq R \otimes \alpha$ , then by definition for all  $t$ :

$$R(t) \leq (R \otimes \alpha)(t) = \inf_u \{R(t - u) + \alpha(u)\}.$$

As this inequality holds for the infimum over all  $u$ , it will also hold for *any*  $u$ , especially also for  $u = t - s$  with *arbitrary*  $s$ . With this, we get

$$\begin{aligned} R(t) &\leq R(t - (t - s)) + \alpha(t - s) \\ \implies R(t) - R(s) &\leq \alpha(t - s), \end{aligned}$$

which is what we had to show for the first property: The inequality holds for *all*  $s$  and  $t$ .

b) Similarly, with the definitions from the lecture and the exercise sheet we get for all  $t$

$$R^*(t) \geq (R \otimes \beta)(t) = \inf_u \{R(t - u) + \beta(u)\}.$$

Let  $u_0$  be the  $u$  realizing the infimum, and let  $s := t - u_0$ , i.e.  $u_0 = t - s$ . Replacing  $u$  by  $u_0$  and removing the infimum yields

$$\begin{aligned} R^*(t) &\geq R(t - (t - s)) + \beta(t - s) \\ \implies R^*(t) - R(s) &\geq \beta(t - s). \end{aligned}$$

Thus, for all  $t$  there exists some  $s := t - u_0$  fulfilling the inequality, which is exactly what we had to show.

### 2 Power-Down Mechanisms

As mentioned in the hint, we only focus on a single idle period because if we know that our algorithm is  $c$ -competitive for any idle period, we also know that it is  $c$ -competitive for the complete busy sequence.

a) Analogously to the 2-competitive ski-rental online algorithm, we consider an algorithm ALG that powers down after  $D$  time units. To see that ALG is 2-competitive, we distinguish two cases for the length of the current idle period  $T$ :

- $T < D$ : The energy consumed by both algorithms is  $c_{\text{ALG}} = c_{\text{OPT}} = T$ , hence the competitive ratio is  $c = T/T = 1$ .
- $T \geq D$ : We have  $c_{\text{ALG}} = D + D$  since ALG waits  $D$  time units and then powers-down and  $c_{\text{OPT}} = D$  because OPT powers down immediately. Hence we get

$$c = \frac{2D}{D} = 2 .$$

b) Let ALG be any *deterministic* power down algorithm. Then the time  $t_{\text{ALG}}$  after which it powers down in an idle period is known in advance. The “worst” idle period ends immediately after ALG has powered down, that is we have  $T = t_{\text{ALG}} + \varepsilon$ . Again, we distinguish two cases with respect to the time  $t_{\text{ALG}}$  when ALG powers down.

- $t_{\text{ALG}} < D$ : We have  $c_{\text{ALG}} = t_{\text{ALG}} + D$  and  $c_{\text{OPT}} = t_{\text{ALG}} + \varepsilon$ , hence

$$c = \frac{t_{\text{ALG}} + D}{t_{\text{ALG}} + \varepsilon} = 1 + \frac{D - \varepsilon}{t_{\text{ALG}} + \varepsilon} > 2 \quad \text{for } \varepsilon \rightarrow 0$$

since  $t_{\text{ALG}} < D$ .

- $t_{\text{ALG}} \geq D$ : We have  $c_{\text{ALG}} = t_{\text{ALG}} + D$  again and  $c_{\text{OPT}} = D$ , hence

$$c = \frac{t_{\text{ALG}} + D}{D} = 1 + \frac{t_{\text{ALG}}}{D} \geq 2 \quad \text{for } \varepsilon \rightarrow 0$$

since  $t_{\text{ALG}} \geq D$ .

Hence, ALG cannot be better than 2-competitive.

c) Let ALG be a randomised algorithm that powers down at time  $\frac{2}{3}D$  with probability  $\frac{1}{2}$  and at time  $D$  otherwise. Let  $C_{\text{ALG}}$  be a random variable for the cost incurred by the algorithm. We again consider an arbitrary idle period of length  $T$ . We distinguish three cases:

- $T < \frac{2}{3}D$ : The energy consumption of both algorithms is  $c_{\text{ALG}} = c_{\text{OPT}} = T$ , hence  $c = T/T = 1 < 2$ .
- $\frac{2}{3}D \leq T < D$ : The expected energy consumption of ALG is

$$\mathbf{E}[C_{\text{ALG}}] = \frac{1}{2} \left( \frac{2}{3}D + D \right) + \frac{1}{2}T = \frac{5}{6}D + \frac{1}{2}T$$

and further  $c_{\text{OPT}} = T$ . Hence we get

$$c = \frac{\frac{5}{6}D + \frac{1}{2}T}{T} = \frac{1}{2} + \frac{5}{6} \cdot \frac{D}{T} \leq \frac{1}{2} + \frac{5}{6} \cdot \frac{D}{\frac{2}{3}D} = \frac{1}{2} + \frac{5}{4} = \frac{7}{4} < 2 .$$

- $T \geq D$ : We have for the expected energy consumption of ALG

$$\mathbf{E}[C_{\text{ALG}}] = \frac{1}{2} \left( \frac{2}{3}D + D \right) + \frac{1}{2}(D + D) = \frac{5}{6}D + D = \frac{11}{6}D$$

and further  $c_{\text{OPT}} = D$ . Hence we get

$$c = \frac{\frac{11}{6}D}{D} = \frac{11}{6} < 2 .$$

Hence, the randomised algorithm is  $\frac{11}{6}$ -competitive which is better than any deterministic algorithm.

*Note:* This result, however, is not optimal yet. The best randomised algorithm uses a continuous probability distribution for the shutdown time and thereby achieves a competitive ratio of  $e/(e-1) \approx 1.58$ .